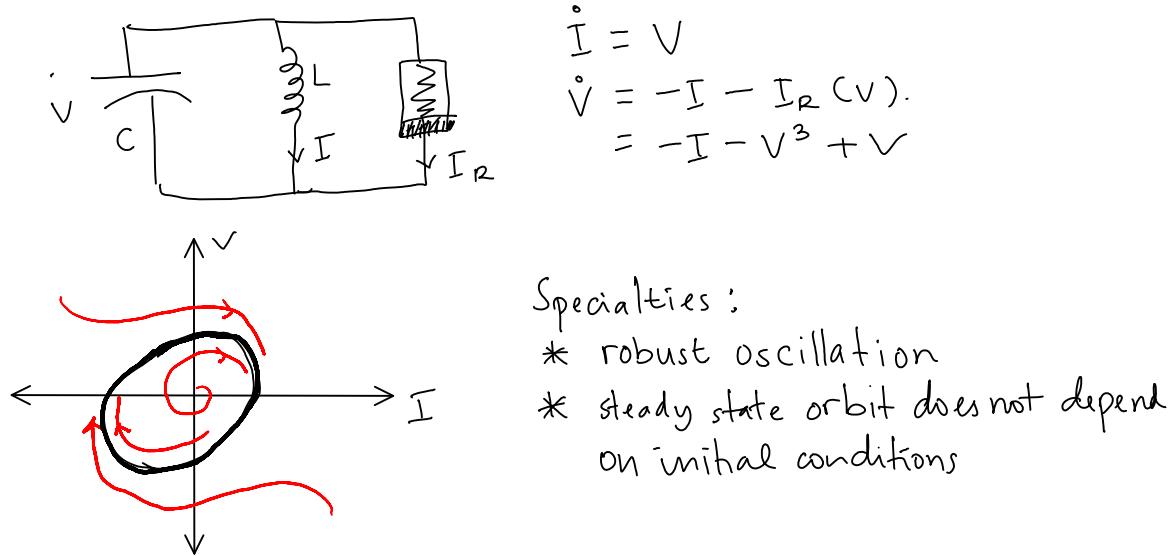


## Limit cycles & Periodic Orbits

Consider the oscillator system from previous lectures:



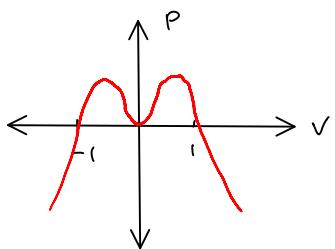
Potential Energy analysis:

Recall that the potential energy is given by:

$$P(I, V) = \frac{1}{2} I^2 + \frac{1}{2} V^2$$

Therefore:

$$\begin{aligned}\frac{dP}{dt} &= I \cdot \dot{I} + V \cdot \dot{V} = IV + V(-I - V^3 + V) \\ &= -V^4 + V^2 = -V^2(V-1)(V+1)\end{aligned}$$



For small  $V$  ( $\|V\| < 1$ ), potential energy increases. For large  $V$ , it decreases

Autonomous system  $\dot{x} = F(x)$ ,  $x \in \mathbb{R}^2$

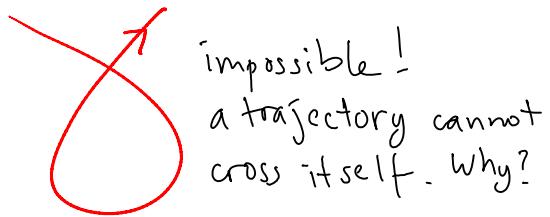
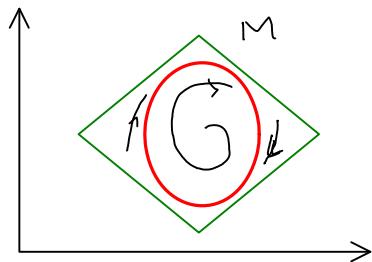
Periodic motion: There exists a  $T > 0$  such that  
 $x(t+T) = x(t)$ , for all  $t$

Two sufficient criteria about the existence of periodic orbits for planar systems:

- \* Poincaré - Bendixson (existence)
- \* Bendixson (non existence)

Poincaré - Bendixson criterion: Suppose that a closed and bounded set  $M \subset \mathbb{R}^2$  is such that:

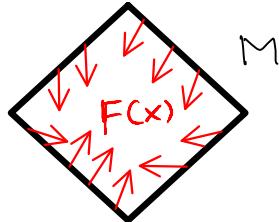
1.  $M$  does not contain any equilibrium or just one equilibrium which is an unstable node or focus, and
2. Every trajectory starting in  $M$  remains in  $M$  indefinitely, then:  $M$  contains a periodic orbit



Example: Harmonic oscillator

Condition #2:  $M$  is invariant. How to check this?

A. Show that the vector field  $F(x)$  on the boundary of  $M$  points inward or tangent to the boundary.



B. Use a potential-like function  $V(x)$ . If  $V(x)$  satisfies:

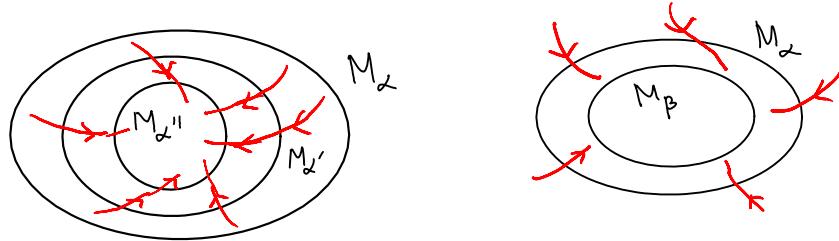
$$\frac{dV}{dt} = \frac{\partial V}{\partial x} \cdot \frac{dx}{dt} = \frac{\partial V}{\partial x} \cdot F(x) \leq 0, \forall x$$

then the level sets  $M_\alpha = \{x \mid V(x) \leq \alpha\}$  is invariant for any  $\alpha$ .

A weaker version:

$$\frac{dV}{dt} = \frac{\partial V}{\partial x} \cdot \frac{dx}{dt} = \frac{\partial V}{\partial x} \cdot F(x) \leq 0, \forall x \text{ s.t } V(x) \geq \beta$$

then the level sets  $M_\alpha = \{x \mid V(x) \leq \alpha\}$  is invariant for  $\alpha \geq \beta$



Example : [ 2.8 from the book ]

$$\begin{aligned}\dot{x}_1 &= x_1 + x_2 - x_1(x_1^2 + x_2^2) \\ \dot{x}_2 &= -2x_1 + x_2 - x_2(x_1^2 + x_2^2)\end{aligned}$$

There is only one equilibrium:  $(0,0)$ . The Jacobian is:

$$\frac{\partial F}{\partial x} = \begin{bmatrix} 1 - (x_1^2 + x_2^2) - 2x_1^2 & 1 - 2x_1 x_2 \\ -2 - 2x_1 x_2 & 1 - (x_1^2 + x_2^2) - 2x_2^2 \end{bmatrix}$$

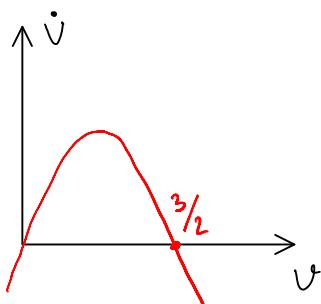
$$\left. \frac{\partial F}{\partial x} \right|_{x=(0,0)} = \begin{bmatrix} 1 & 1 \\ -2 & 1 \end{bmatrix} \rightarrow \text{Eigenvalues} = 1 \pm i\sqrt{2}$$



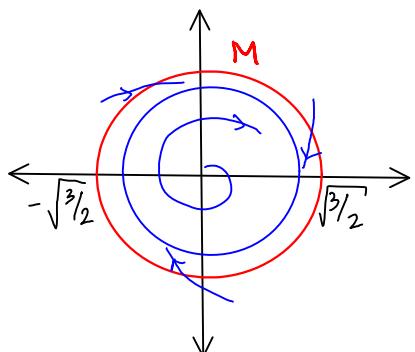
Consider the "potential" function  $V(x) = x_1^2 + x_2^2$ .

$$\frac{dV}{dt} = \begin{bmatrix} 2x_1 \\ 2x_2 \end{bmatrix}^T \cdot F(x) = 2x_1^2 + 2x_1x_2 - 2x_1^2(x_1^2 + x_2^2) + \\ - 4x_1x_2 + 2x_2^2 - 2x_2^2(x_1^2 + x_2^2)$$

$$\text{use } (-2\lambda_1\lambda_2 \leq x_1^2 + x_2^2) \rightarrow \\ = 2x_1^2 + 2x_2^2 - 2(x_1^2 + x_2^2)^2 - 2x_1x_2 \\ \leq 3x_1^2 + 3x_2^2 - 2(x_1^2 + x_2^2)^2 \\ = 3V - 2V^2$$



Thus all level sets  $V(x) \leq \alpha$  are invariant for  $\alpha \geq 3/2$ .



Using Poincaré-Bendixson criterion we can show that any  $M_\alpha$  with  $\alpha > 3/2$  contains a periodic orbit.

Bendixson criterion: Take a planar system

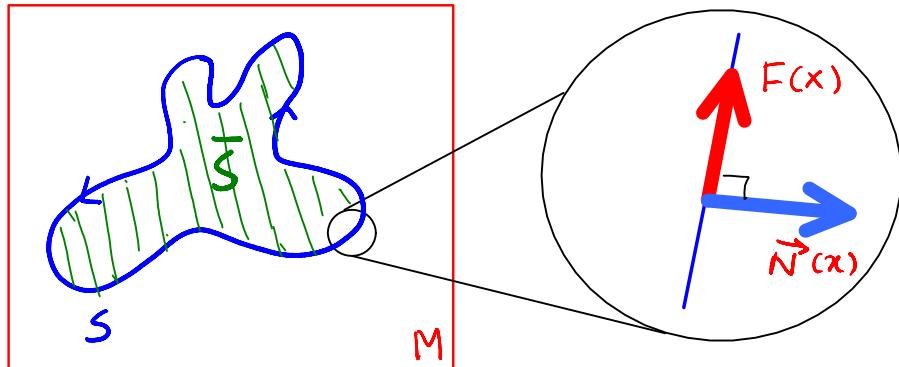
$$\begin{aligned}\dot{x}_1 &= F_1(x_1, x_2) \\ \dot{x}_2 &= F_2(x_1, x_2)\end{aligned}$$

If  $\left( \frac{\partial F_1}{\partial x_1} + \frac{\partial F_2}{\partial x_2} \right)$  is not identically zero and does not change

sign in a simply connected region  $M$ , then  $M$  does not contain

any periodic orbit.

Proof: By contradiction. Suppose that  $M$  contains a periodic orbit  $S$ .



$$\int_S \vec{F}(x) \cdot \vec{N}(x) dx = 0 \quad (\text{Integrate the flux of } F(x) \text{ along } S)$$

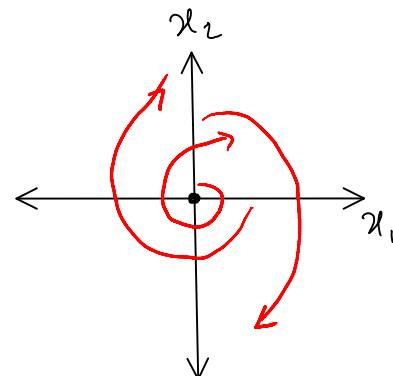
But, according to Green's theorem:

$$\begin{aligned} \int_S \vec{F}(x) \cdot \vec{N}(x) dx &= \iint_S \operatorname{div}(F) dxdy \\ &= \iint_S \left( \frac{\partial F_1}{\partial x_1} + \frac{\partial F_2}{\partial x_2} \right) dxdy \neq 0 \end{aligned}$$

Examples:

$$\begin{aligned} \dot{x}_1 &= x_2 \\ \dot{x}_2 &= -x_1 - x_1^3 + x_2 \end{aligned}$$

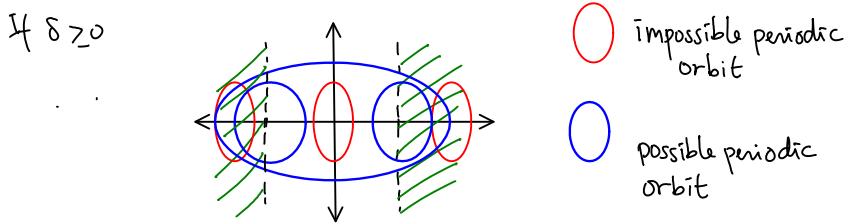
$$\operatorname{div}(F) = 1 > 0 \rightarrow \text{no periodic orbit}$$



Example:  $\dot{x}_1 = x_2$   
 $\dot{x}_2 = -\delta x_2 + x_1 - x_1^3 + x_1^2 x_2$

Equilibria =  $(-1, 0)$ ,  $(0, 0)$ ,  $(1, 0)$

$\text{div}(F) = -\delta + x_1^2 \rightarrow$  if  $\delta < 0$ , no periodic orbit



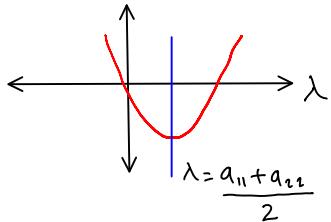
Application to linear systems: Let  $\dot{x} = Ax$ , where  $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$

$\text{div}(F) = a_{11} + a_{22}$ , thus periodic orbits are possible only if

$$a_{11} + a_{22} = 0$$

Graphical explanation: The characteristic polynomial  $\det(\lambda I - A) = (\lambda - a_{11})(\lambda - a_{22}) - a_{12}a_{21}$

$$= \lambda^2 - (a_{11} + a_{22})\lambda + a_{11}a_{22} - a_{12}a_{21}$$

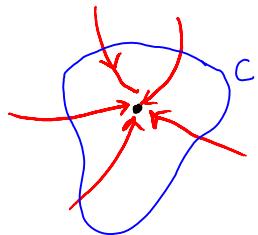


## Index Theory

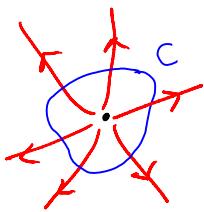
$$\dot{x} = F(x), x \in \mathbb{R}^2$$

Take any closed curve  $C$  in  $\mathbb{R}^2$  that does not pass through any equilibrium (not necessarily a trajectory). The index of  $C$  is the number of full circles made by  $F(x)$  (in counter clockwise direction) as we traverse  $C$  counter clockwise.

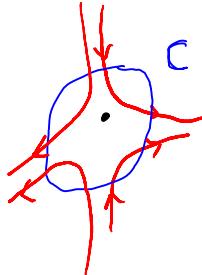
Examples:



$$\text{Index } C = 1$$



$$\text{Index } C = 1$$



$$\text{Index } C = -1$$

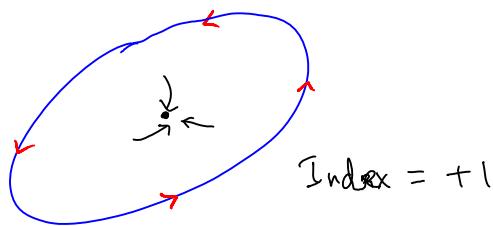
Lemma: The index of a node, focus, or a center is +1

The index of a saddle point is -1

The index of a closed trajectory is +1

The index of a closed curve is the sum of the indices of the equilibria in it.

Corollary: Inside any closed trajectory, there must be a non-saddle point equilibrium.



$$\text{Index} = +1$$

Example:  $\dot{x}_1 = -x_1 + x_1 x_2$   
 $\dot{x}_2 = x_1 + x_2 - 2x_1 x_2$

There are two equilibria  $(0,0)$  and  $(1,1)$

Computing the Jacobian:  $\frac{\partial F}{\partial x} = \begin{bmatrix} -1+x_2 & x_1 \\ 1-2x_2 & 1-2x_1 \end{bmatrix}$

$$\left. \frac{\partial F}{\partial x} \right|_{x=(0,0)} = \begin{pmatrix} -1 & 0 \\ 1 & 1 \end{pmatrix} \rightarrow \text{eigenvalues} = \pm 1 \text{ saddle point}$$

$$\left. \frac{\partial F}{\partial x} \right|_{x=(1,1)} = \begin{pmatrix} 0 & 1 \\ -1 & -1 \end{pmatrix} \rightarrow \text{eigenvalues} = \frac{-1 \pm \sqrt{3}}{2} \text{ stable}$$

