

# Intro to ECSE Class 11: Diodes and Differential Resistance

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## I] Overview of Lab 02: Parts A & B

1. Introduce the concept of **linearity**
2. Give you another tool for solving and designing circuits: **nodal analysis**
3. Provide an example of non-linearity: **diodes**

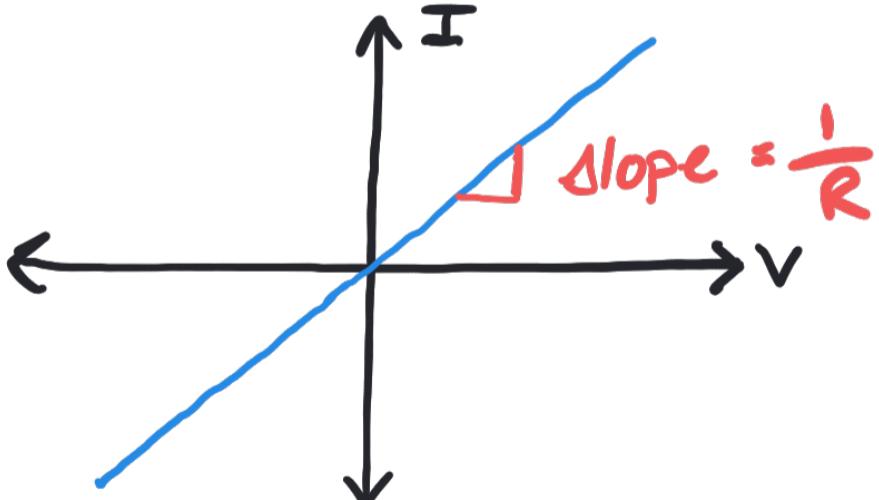
Part A: Defining Linear & Non-Linear Device IV Characteristics (today)

Part B: Solving Linear Resistive Networks Using Nodal Analysis

## II] Linear and Non-Linear IV Characteristics

### 1. Resistor

- IV Characteristic



$$V = IR$$

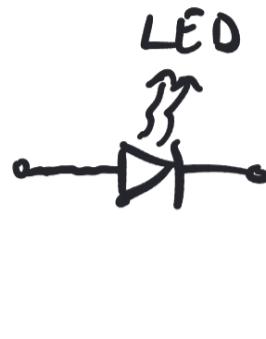
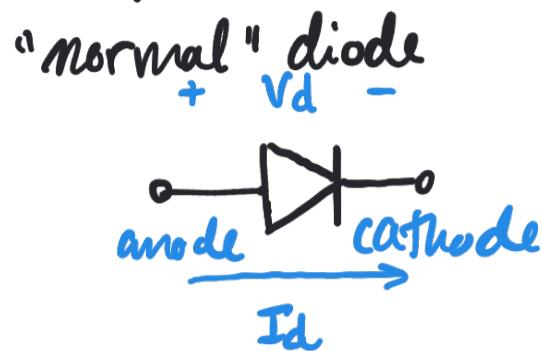
$$\Delta V = R \Delta I$$

$$\text{Slope: } \frac{\Delta I}{\Delta V} = \frac{1}{R}$$

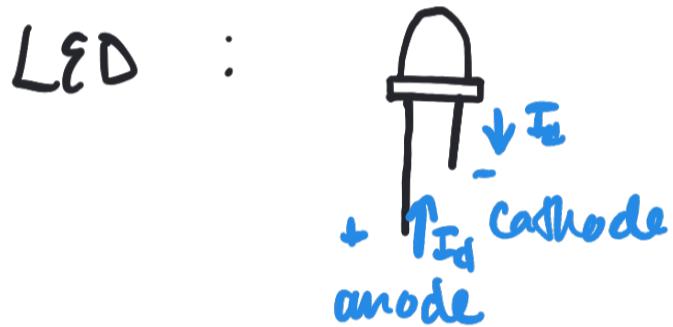
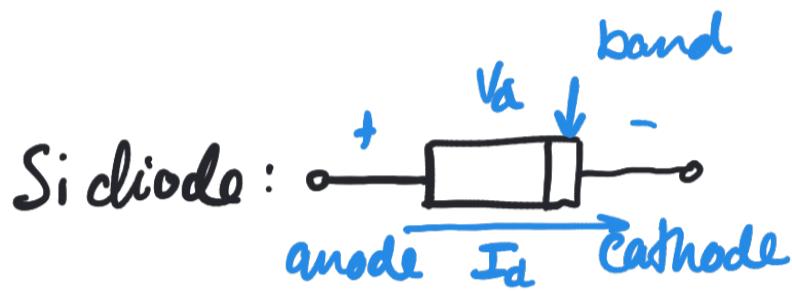
- $V = IR \rightarrow$  straight line  $\rightarrow$  linear component

2. Diode : allows current to flow in only one direction<sup>2</sup>

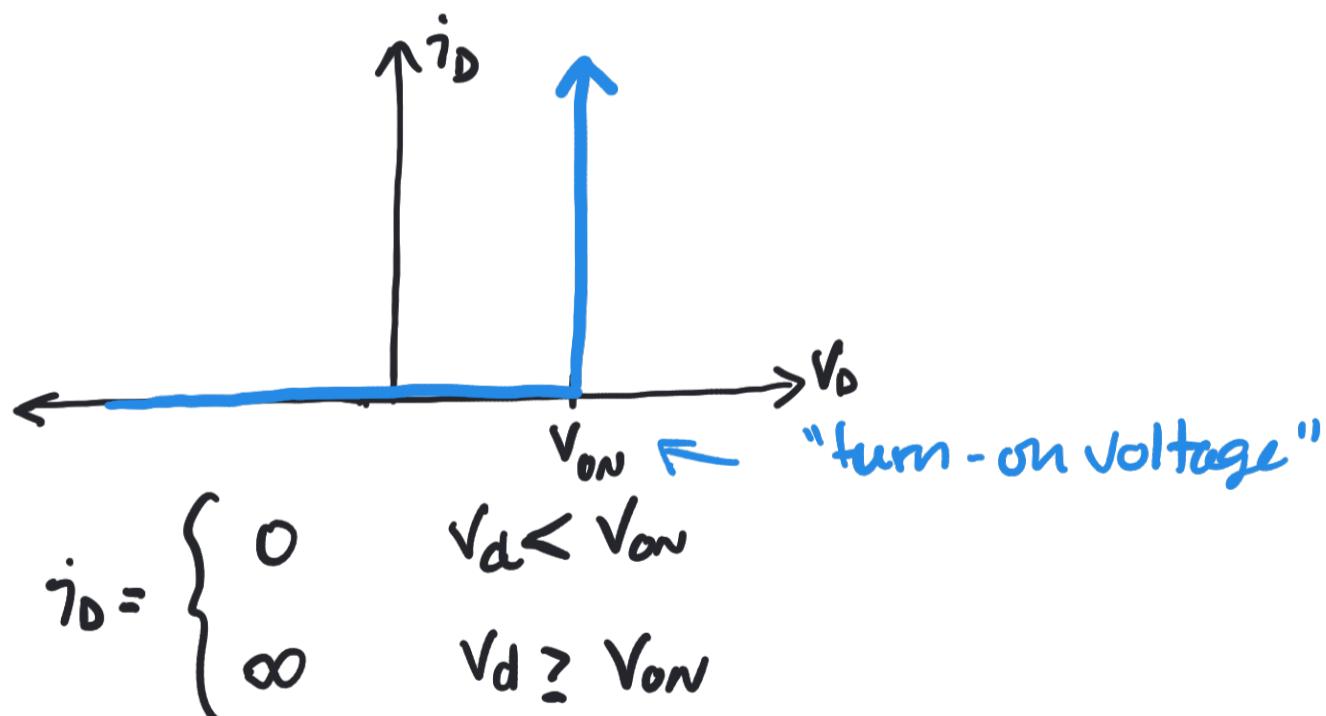
a) Circuit symbol



- actual part appearance



b) Model #1: Simple ideal diode model



- Turn-on voltage  $V_{on}$  : voltage when current starts to flow

- Typical values of  $V_{on}$

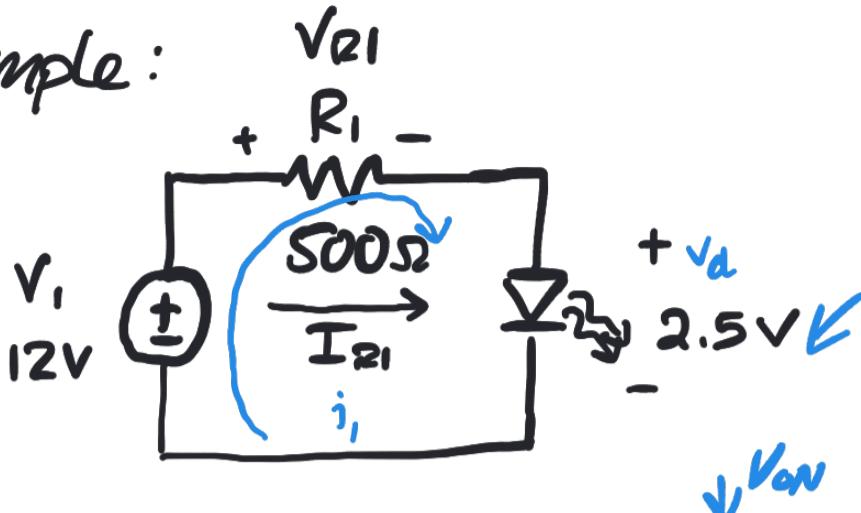
- Si : 0.7V

- LEDs: 1.5V+ → depends on color

- useful for simple analysis of diode circuits

Example:

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- Find  $V_{R1}$  and  $I_{R1}$

$V_{ON} = 2.5V$  - fixed regardless of current

- Use KVL:  $-12V + V_{R1} + 2.5V = 0 \rightarrow V_{R1} = 9.5V$
- Use Ohm's Law:  $I_{R1} = \frac{V_{R1}}{R_1} = \frac{9.5V}{500\Omega} = 19mA$

### c) The actual ideal diode model

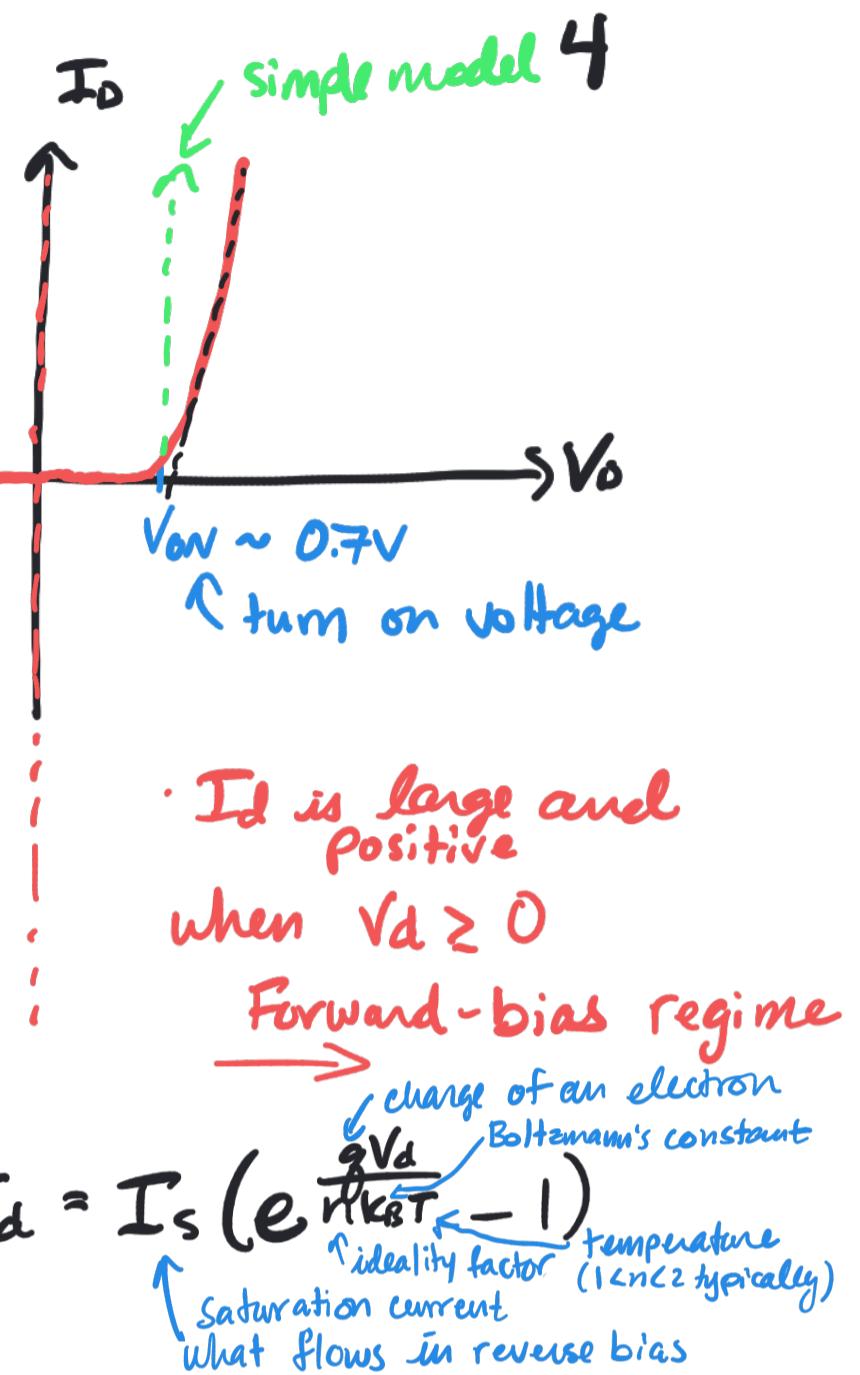
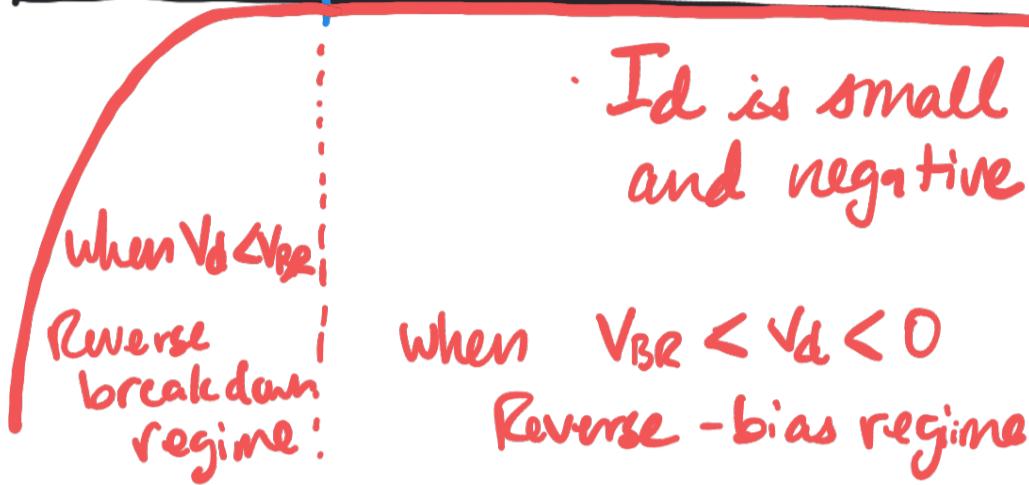
- Differences compared to simple model

- $I_d$  is not infinity for  $V_d > V_{ON}$  (resistance of IV curve is not 0)

- Current flows in the "wrong" direction
- If  $V_d < V_{ON}$ , a small negative current flows  
↳  $I_s$ : saturation current
  - If  $V_d < V_{BR}$  (reverse breakdown voltage), a large negative current will flow

## IV Characteristic

$I_d$  is large and negative  $\downarrow$   
reverse breakdown voltage  
 $V_{BR} \sim -100V$  typically



Ideal diode equation:

$$I_d = I_s (e^{\frac{qVd}{nKT}} - 1)$$

In forward bias  $V_d > V_{ON}$

$$I_d \sim I_s e^{\frac{qVd}{nKT}}$$

In reverse bias  $V_d < 0$

$$I_d \sim -I_s$$

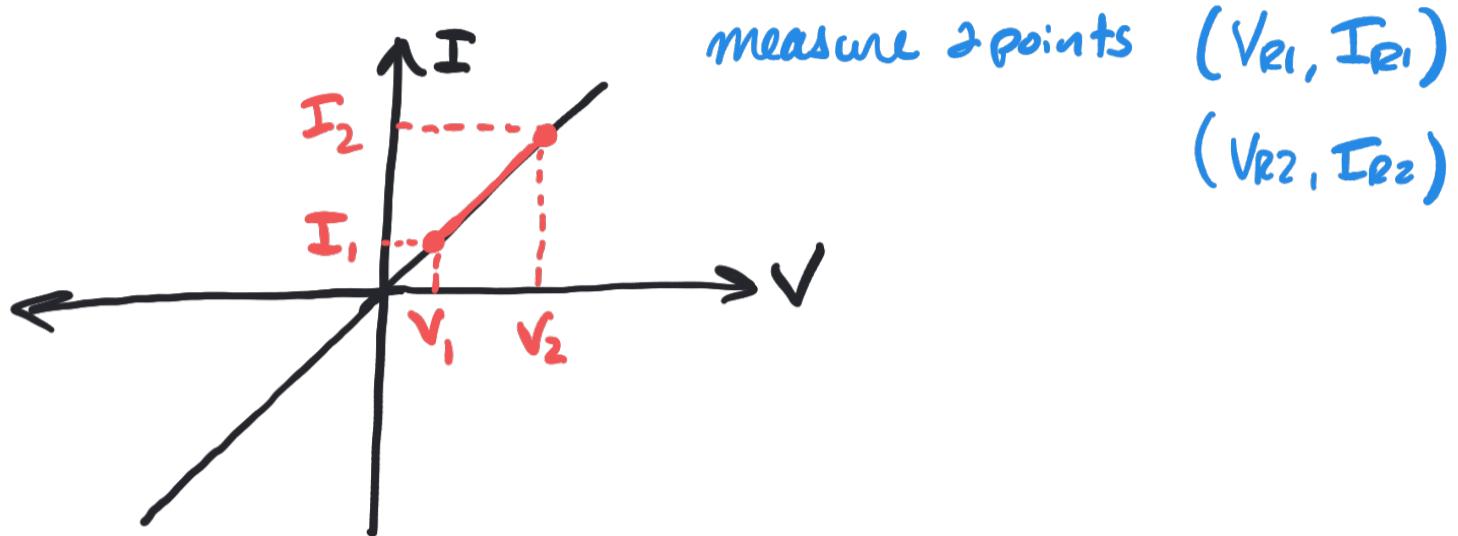
In reverse breakdown: not in equation

### 3. Differential Resistance

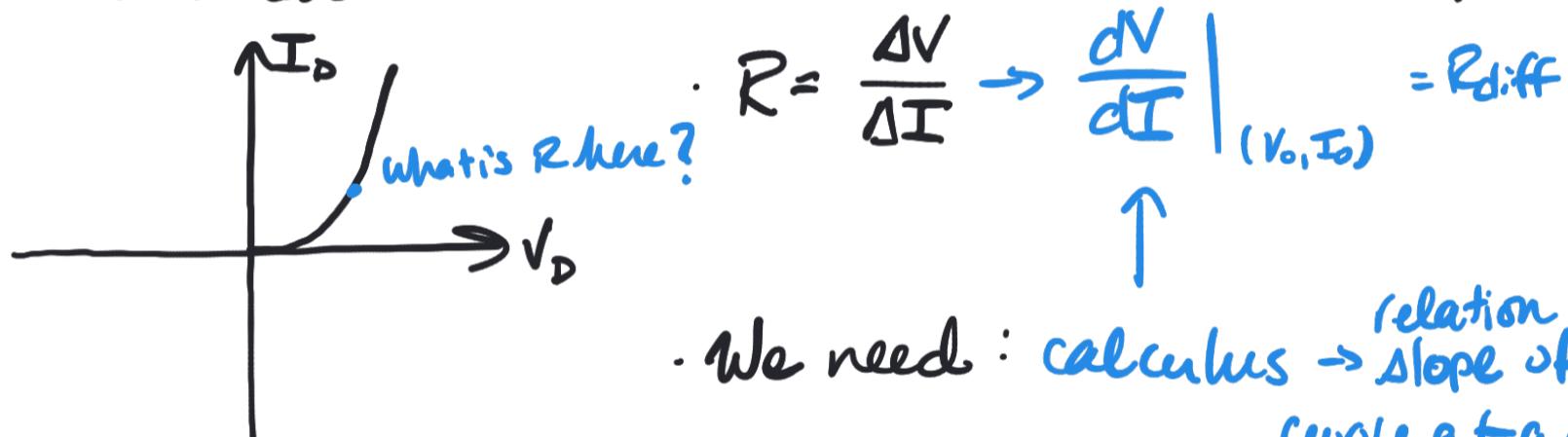
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- So far we have defined resistance on an IV characteristic as  $R = \frac{\Delta V}{\Delta I}$

$$\text{or } R = \frac{V_{R2} - V_{R1}}{I_{R2} - I_{R1}} = \frac{\Delta V}{\Delta I}$$



- But what about non-linear IV Characteristics?



We need: calculus  $\rightarrow$  slope of IV curve at a point  $(V_0, I_0)$

- Differential Resistance: local measure of resistance how much does  $V$  change <sup>(ΔV)</sup> for a small change in  $I$  ( $dI$ )

$$R_{\text{diff}} = \frac{dV}{dI} \Big|_{(V_0, I_0)} \rightarrow V = IR$$

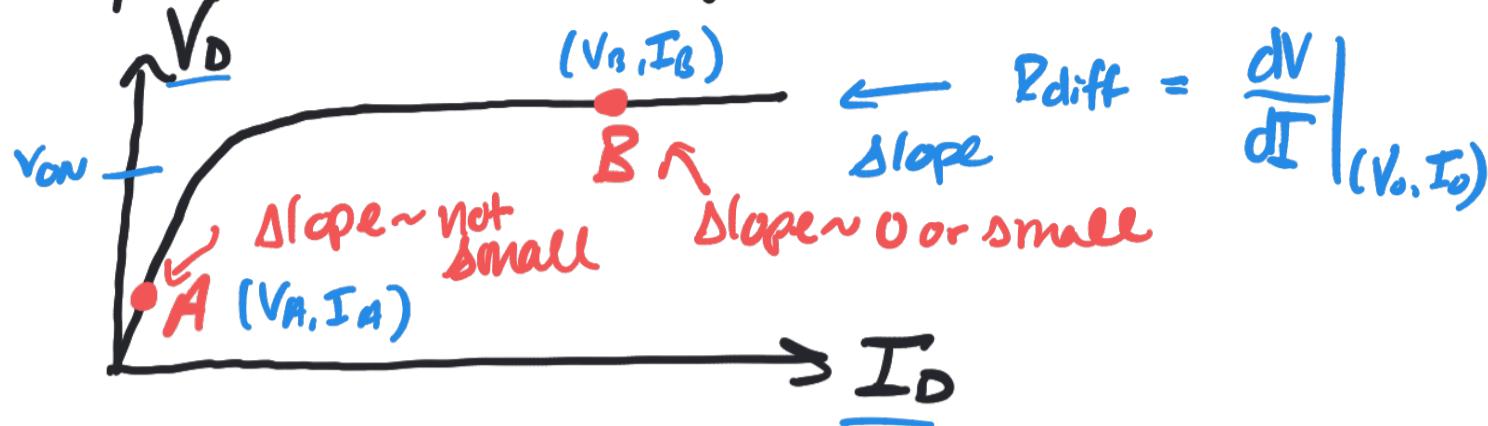
$$\frac{d}{dI}(V) = \frac{d}{dI}(IR)$$

- What is "resistance" then?

- It's how much  $V$  changes for a change in  $I$

$$\frac{dV}{dI} = R$$

## Example: diode in forward-bias



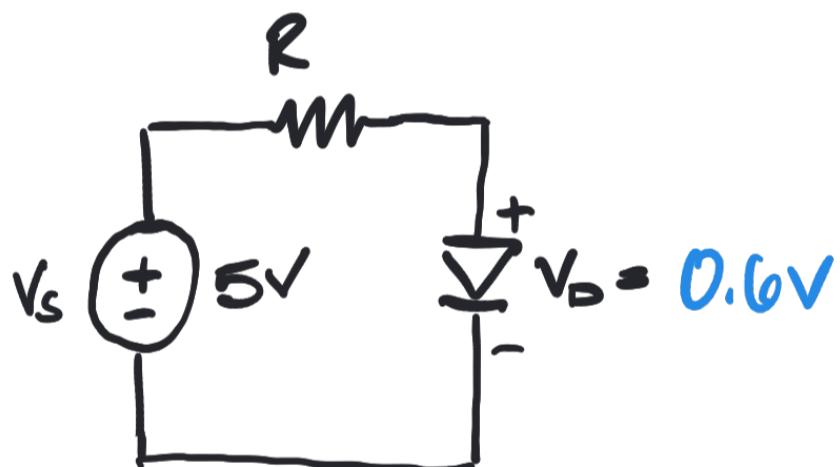
- At which point is  $R_{\text{diff}}$  smaller?
  - $R_{\text{diff}}$  for a diode is very small for  $V_d > V_{\text{on}}$   
small changes in  $V_d$  lead to large changes in  $I_d$
- Consequences of varying differential resistance for diodes:
  - Voltage vs. current control: it's difficult to drive a diode at a constant voltage & current using voltage
  - drive a diode with current
  - current limiting:
    - If we give a diode too much current it can break. We should put a resistor in series with the diode to keep the current at a safe level



## 4. Current-Limiting Resistor

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- Given the max. current & turn-on voltage of a diode, we can choose a resistor to limit the current to a safe value
- How do we find the max. current for a diode?
  - $I_{max} = 300mA$
  - $V_{on} = 600mV @ 1mA$



$$4.4V = V_R$$

Choose  $R$  so that  $I_d \ll 300mA$

say  $I_R = 150mA$

$$R = \frac{V_R}{I_R} = \frac{4.4V}{150mA} = \underline{\underline{30\Omega}}$$

- What value of  $R$  will limit the current to a safe value? for this case  $R > 30\Omega$  typically we use  $R \sim 100\Omega$